## Modelling of Moving Load on Embankment

# For LUSAS version:21.0For software product(s):LUSAS Bridge plusWith product option(s):Geotechnical, Nonlinear

### **Problem Description**

This example aims to study the impact of a load in motion on an embankment. The model includes four layers: soft rock, base and sub-base, and reinforced road bed. The total length of the load track being analysed is 50 meters.

#### Keywords

Moving Load, Settlement.

#### **Associated Files**

Associated files can be downloaded from the user area of the LUSAS website.



**moving\_load.lvb** carries out automated modelling of the example.

- Use File > New to create a new model of a suitable name in a chosen location.
- Use File > Script > Run Script to open the lvb file named above that was downloaded and placed in a folder of your choosing.

#### **Objectives**

The goal of this example is to demonstrate the process of incorporating a moving load into a model and determining the settlement of the load along its path.

#### **Preparing the Model Features**

The user has to create a new model, set the Analysis category as 3D, and specify the model units as kN,m,t,s,C.

#### **Feature Geometry**

The model is generated by creating surfaces on the XZ plane and then extrude them along the Y axis. By utilizing the Copy and Sweep command, the time required to create the model is considerably reduced. However, it is essential to be diligent in ensuring that the surfaces are properly connected and that there are no overlaps (Figure 1 and 2).



#### **Preparing the Model Attributes**

Model attributes (mesh, material, geometric properties, etc.) are defined and assigned to the model. Figure 3 shows the attributes of model.



#### **Defining the Mesh**

Hexahedral, quadratic stress elements (HX20) have been used for meshing (Figure 4)



Figure 4: Mesh and boundary conditions

#### **Defining the Materials**

An isotropic elastic material is used for the reinforced road bed while other materials have been assigned nonlinear behaviour based on the Modified Mohr-Coulomb failure surface. All material properties are listed in table 1.

#### **Table 1: material properties**

| Layer       | Mass<br>Density      | Young's<br>modulus, E | Poisson's<br>ratio, v | Angle of friction, $\phi$ | Angle<br>of<br>dilation,<br>$\psi$ | Cohesion,<br>c | $\mathrm{K}_{\mathrm{0}}$ |
|-------------|----------------------|-----------------------|-----------------------|---------------------------|------------------------------------|----------------|---------------------------|
| Road<br>bed | 1.9 t/m <sup>3</sup> | 2.1E6 kPa             | 0.25                  | -                         | -                                  | -              | 0.333                     |
| Base        | 1.9 t/m <sup>3</sup> | 1.0E3 kPa             | 0.35                  | 31°                       | 0°                                 | 20 kPa         | 0.485                     |
| Sub-base    | 2.0 t/m <sup>3</sup> | 100.0E3kPa            | 0.3                   | 40°                       | 0°                                 | 1 kPa          | 0.357                     |
| Soft rock   | $2.2 \text{ t/m}^3$  | 1.2E6 kPa             | 0.28                  | 37°                       | 0°                                 | 10 kPa         | 0.398                     |

#### **Defining the Supports**

The model is restrained in X and Y direction, and fully fixed supports have assigned to the base (Figure 4)

#### **Defining the Loads**

In addition to gravity, we also created point loads which apply concentrated force at specific points. These point loads can be defined individually or as a set of discrete point loads in 3D space, each with a different magnitude. In this example, all point loads are defined using a grid and have a value of 150 kPa (Figure 5).

| Poir | nt                  |                   |             |                           | $\times$ |
|------|---------------------|-------------------|-------------|---------------------------|----------|
| A    | nalysis category 30 | )                 |             |                           |          |
|      |                     | Untransformed loa | d direction | Projection vector         |          |
| C    | Arbitrary           | ⊖x ⊖xyz           |             | Project in load direction |          |
| c    | Grid x 2            | OY OSurfa         | ce normal   | Project for prestress     |          |
| y 2  |                     |                   |             | X component 0.0           |          |
|      |                     | - Oz              |             | Y component 0.0           |          |
|      |                     |                   |             | Z component 1.0           |          |
|      | x                   | Y                 | Z           | Load                      |          |
| 1    | -0.75               | -1.0              | 3.2         | -150.0                    |          |
| 2    | -0.75               | 1.0               | 3.2         | -150.0                    |          |
| 3    | 0.75                | 1.0               | 3.2         | -150.0                    |          |
| 4    | 0.75                | -1.0              | 3.2         | -150.0                    |          |
|      |                     |                   |             |                           |          |
|      |                     |                   |             |                           |          |
|      |                     |                   |             |                           |          |
|      |                     |                   |             |                           |          |
| -    |                     |                   |             |                           |          |
|      | Name Moving         | Load              |             | × (2)                     |          |
|      | Nume                |                   |             | • (2)                     |          |
|      |                     |                   |             |                           |          |
|      |                     | Chan              | Connect     | Analy Units               |          |
|      |                     | Close             | Cancer      | Арріу Неір                |          |

**Figure 5: Discrete Points Load** 

#### **Defining Other Attributes**

When using a discrete loading to represent a vehicle passing across a structure it is necessary to target the application of the load onto the model using a Search Area (Figure 6).



**Figure 6: Discrete Points Load** 

Note. The distribution of load to the nodes follows the shape functions of the particular element. In quadratic elements, this distribution can appear at first unlikely. For example, a unit positive load at the centre of an 8-noded quadratic element, results in negative 0.25 loads at the corners and positive 0.5 loads at the mid-side nodes (LUSAS Help).

We reset the deformation in the first load case via **Reset Deformation** attribute.

#### **Running the Analysis**

We consider the following stages:

#### **Initial Phase**

This stage simulates the initial conditions where **Gravity** is applied as a load, the moving load has not yet initiated. Nonlinear analysis control properties are defined for this phase, all the parameters are left at their default values.

#### **Moving Load Phases**

In LUSAS, the moving load generator is used to create many load cases resulting from a vehicle moving along a defined path. To access this tool, use **Bridge > Moving Load Analysis**, which will bring up a dialog box with parameters such as "search area", "reference path," and "path division" (Figure 7). These parameters can be used to customise the load cases with the moving load. The search area "Srch1" has already been created (Figure 6) and the user can preselect the path of the moving load (line 93) before launching the dialog. There are 26 stages that represent the movement of the load along the path, which is illustrated in figure 8.

| Discrete load                       | 2:Moving Load                            |                                      |              | ~    |  |
|-------------------------------------|--|--------------------------------------|--------------|------|--|
| ssignment                           |  |                                      |              |      |  |
| O Project onto                      | line (2D line beams and                  | l frames)                            |              |      |  |
| Project over                        | area (grillages, shells, a               | and 3D space fr                      | ames)        |      |  |
|                                     | Search area                              | 1:Srch1                              |              | ```  |  |
| Options for load                    | s outside search area                    | Include Full L                       | oad          | ```  |  |
|                                     | Moments to include                       | None                                 |              |      |  |
| Reference path<br>Direction of trav | rel                                      | Create reference path from selection |              |      |  |
| ath divisions                       |  |                                      |              |      |  |
| O Move load                         | along path in equal divis                | sions                                | Divisions 26 | \$   |  |
| O Move load                         | oy incremental distance<br>case envelope | along path                           | Distance 1.9 | 2308 |  |
|                                     |  |                                      |              |      |  |
| sterner St                          | atic Moving Load Analysis                | 1                                    |              | · () |  |

Figure 7: Moving Load Analysis



Figure 8: Moving load path

### **Viewing the Analysis**

Analysis loadcase results are present in the Treeview.

#### **Deformed Mesh**

The deformed mesh at stage 11 is depicted in Figure 9.



Figure 9: Deformed mesh at stage 11

#### Settlement

Since soil layers are homogenous, it is expected that the displacement along the moving load's path will be consistent, with a value of about 8-9mm as shown in Figure 10.



Figure 10: Resultant displacement at stage 11 (m)

#### Envelope

An overview of the maximum displacement along the tracking path can be obtained by enveloping loads along that path. This is done by selecting **Analysis > Envelope** (Figure 11).



Figure 11: Envelope resultant displacement